

Quantitative Risk Analysis of High Safety-significant Safety-related DI&C Systems using IRADIC Technology

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Challenges in Addressing CCF in HSSSR DI&C Systems

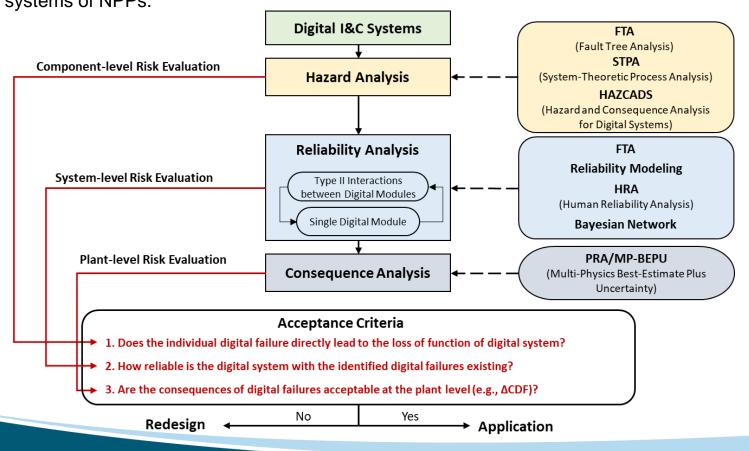
- Some technical challenges remain in software common cause failure (CCF) analysis in the high safety-significant safety-related (HSSSR) DI&C systems:
 - Are current methods able to capture potential CCFs in DI&C systems?
 - Various methods: FMEA, FTA, STPA, HAZCADS, HAZOP...
 - Software should not be analyzed in isolation from the complete digital system.
 - Not easy to identify new failure modes in single software and interactions between different components in a DI&C system ("Type II interaction").
 - Is qualitative evaluation sufficient for addressing software CCFs in HSSSR DI&C systems?
 - Most of the STPA-based approaches focus on the identification of software failures but not the quantification of their probabilities.
 - Instead, a conservative bounding assessment is performed to evaluate their impacts to plant safety (e.g., ∆ Core
 Damage Frequency, [CDF]), which may lead to an underestimation of safety margins gained by plant digitalization.
 - How to quantitatively evaluate CCF-related impacts to DI&C systems and plant response?
 - This proposes a need to develop an integrated strategy to include both qualitative hazard analysis and quantitative reliability and consequence analysis for addressing software CCF issues in the HSSSR DI&C systems of nuclear power plants (NPPs).



Schematic of <u>Integrated Risk Assessment</u> Technology for <u>Digital I&C</u> Systems (IRADIC)

INL-IRADIC Technology:

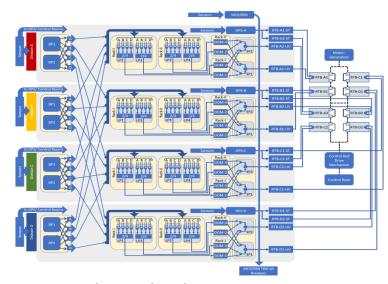
 Provide an integrated and best-estimate capability to address new technical issues quantitatively, accurately, and efficiently in plant modernization progress, such as software CCFs in HSSSR DI&C systems of NPPs.





How IRADIC Could Support Industry for Risk Informing HSSSR DI&C Designs or Upgrades?

- We expect IRADIC to become an integrated risk-informed tool for vendors and utilities to meet regulatory requirements and optimize the diversity and defense-in-depth (D3) applications in the DI&C designs and upgrades.
 - Quantitative vs. Qualitative
 - Software Failure Probability → DI&C System Failure Probability → △CDF
 - Balance of risk and cost in design stage
 - Management strategy of CCFs
 - All elimination vs. selective elimination
 - Level of redundancy
 - 4 divisions vs. 2 divisions
 - 4 vs. 2 local coincidence logic processors per division
 - Level of diversity
 - Design: Analog? Digital? Both?
 - Software: Design requirements, programming language...
 - Equipment: Manufacturers, designs, architectures...



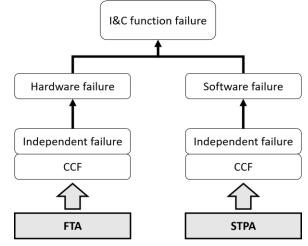
4-division digital Reactor Trip System

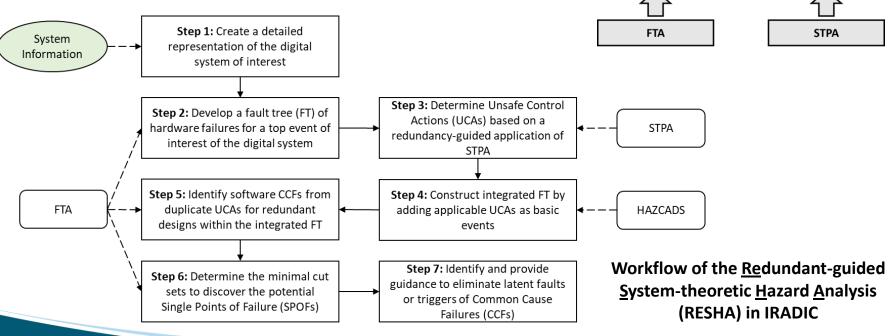


(I). Redundancy-guided System-theoretic Hazard Analysis

Hazard analysis in IRADIC:

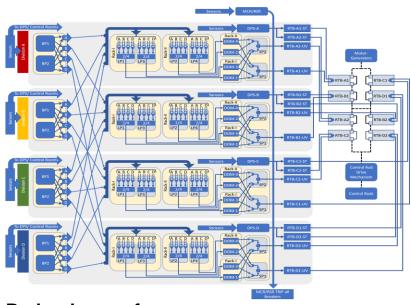
- Incorporates the concept of combining FTA and STPA from HAZCADS.
- Reframes STPA in a redundancy-guided way to address CCF concerns in highly redundant HSSSR DI&C systems.
- Identifies failures in Type II interactions (between different components of a DI&C system).







Determine Unsafe Control Actions (UCAs) Based on a Redundancy-guided Application of STPA



Redundancy of

- Reactor trip breakers
- LCL processors
 - · Division level
 - Unit level (two racks per division)
 - Module level (two processors per rack)
- Bistable processors
 - Division level
 - Unit level (two processors per division)

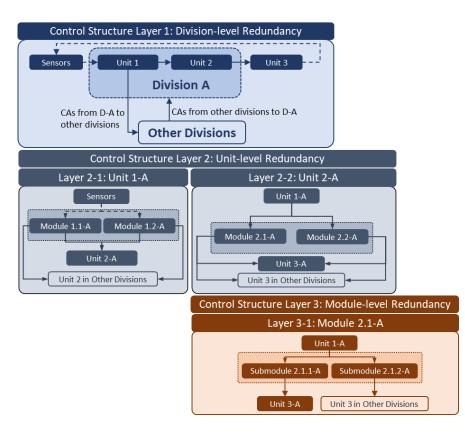


Illustration of a multilayer control structure that captures UCAs in different levels of redundancy

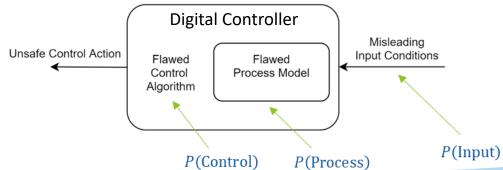


Key CCFs Leading to Potential Single Points of Failure (SPOFs) in the Design

Table 5: First order cut sets for the RPS system.			
Number	Cut set	Description	
1	SP-HD-CCF	Selective processor hardware CCF.	
2	LC-DOM-HD-CCF	Logic cabinet digital output module hardware CCF.	
3	RTB-UV-HD-CCF	Reactor trip breaker undervoltage hardware CCF.	
4	LC-BP-HD-CCF	Logic bistable processor hardware CCF.	
5	LC-LP-HD-CCF	Logic cabinet logic processor hardware CCF	
6	LC-LP-SF-CCF-TA	Logic cabinet logic processor software CCF type A.	
7	LC-LP-SF-CCF-TC	Logic cabinet logic processor software CCF type C.	
8	LC-DOM-SF-CCF-TA	Logic cabinet digital output module software CCF type A.	
9	LC-DOM-SF-CCF-TC	Logic cabinet digital output module software CCF type C.	
10	SP-SF-CCF-TC	Selective processor software CCF type C.	
11	SP-SF-CCF-TA	Selective processor software CCF type A.	
12	LC-BP-SF-CCF-TA	Logic cabinet bistable processor software CCF type A.	
13	LC-BP-SF-CCF-TC	Logic cabinet bistable processor software CCF type C.	

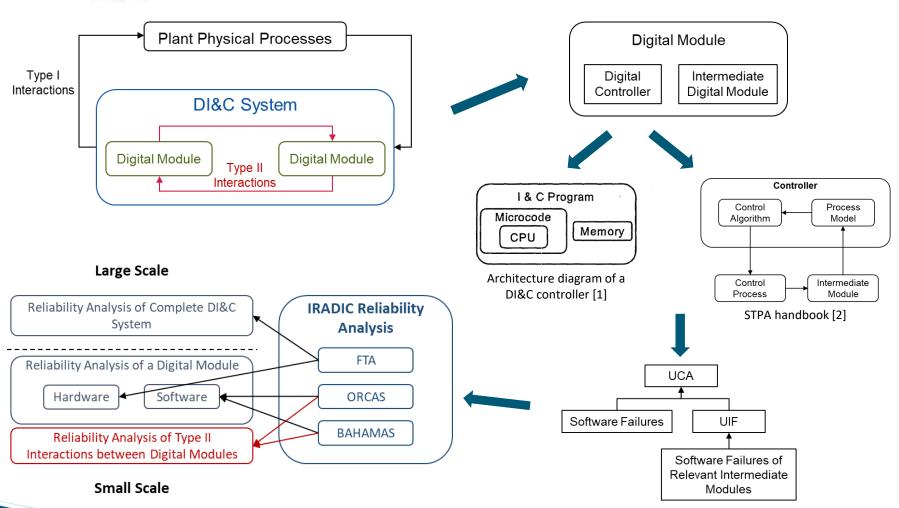
Causal factors of UCAs (e.g., software failures)

- Category 1: Inner software failure
 - Software design defect
 - Software implementation failure
- Category 2: Incorrect feedback or inputs
 - Failures in Type II interactions





Identifying and Quantifying Failures in both Software and Type II Interactions





(II). Quantitative Software Reliability Analysis in IRADIC Technology

Methods developed within IRADIC:

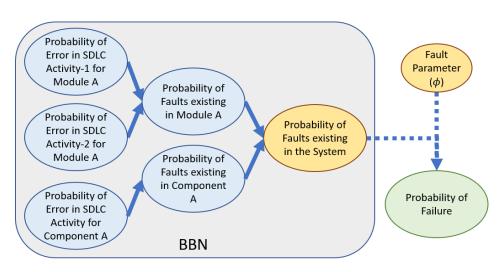
- BAHAMAS (Bayesian and HRA-Aided Method for the Reliability Analysis of Software)
 - Developed for the conditions with <u>limited testing/operational data or for reliability estimations of software in early development stage</u>.
 - Provide a rough estimation of failure probabilities to support the design of software and target DI&C systems.
- ORCAS (Orthogonal Defect Classification for Assessing Software Reliability)
 - Developed for the conditions with <u>sufficient testing/operational data</u>.
 - A relatively accurate estimation of software failure probabilities can be provided.

	BAHAMAS	ORCAS	
Applicable conditions	 Limited testing/operational data For reliability estimations of software in early development stage 	 Sufficient testing/operational data For reliability estimations of software in development or testing stage 	
Key assumption	Software failures can be traced to human errors in the software development life cycle	Sufficient data is available through testing (e.g., T-Way testing)	
Ways to identify root causes	STPA + BBN + HRA in SDLC	STPA + ODC + Metric-based methods	
Ways to quantify failure rate of root causes	HRA in SDLC	Software reliability growth modeling	
		BNN Bayesian Belief Network ODC Orthogonal Defect Classification HRA Human Reliability Analysis SDLC software development life cycle	

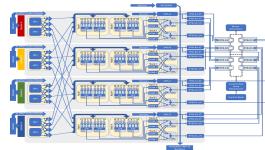


Method 1. <u>Bayesian and HRA-Aided Method for</u> the Reliability <u>Analysis of Software (BAHAMAS)</u>

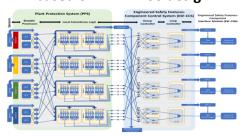
- BAHAMAS quantifies fault tree basic events:
 - **BBN** provides a means of combining disparate causal factors and sources of faults in the system.
 - HRA quantifies root human errors (i.e., causes of faults).
 - The fault parameter converts probability of faults into probability of failure.
 - CCF modeling parameter (Beta-factor method) accounts for single failure and CCFs.
- Instead of relying on testing data, BAHAMAS assumes software failures can be traced to human errors in the SDLC and modeled with HRA.







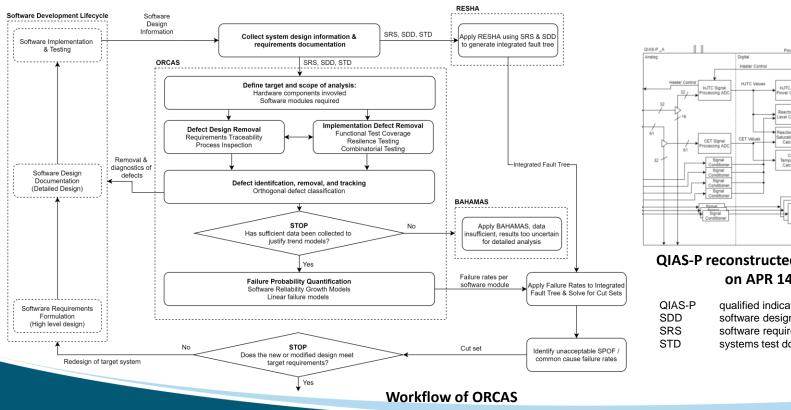
A 4-division digital Reactor Trip System based on APR 1400 design

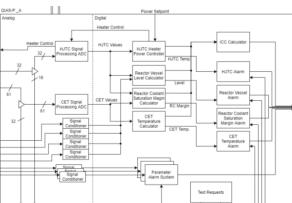




Method 2. Orthogonal Defect Classification for **Assessing Software Reliability (ORCAS)**

- Compared with BAHAMAS, **ORCAS** quantifies FT basic events:
 - Using sufficient operational and testing data when available.
 - Using metric-based and test-based methods to identify software defects.
 - Using ODC systematically to link identified defects with potential failure modes.





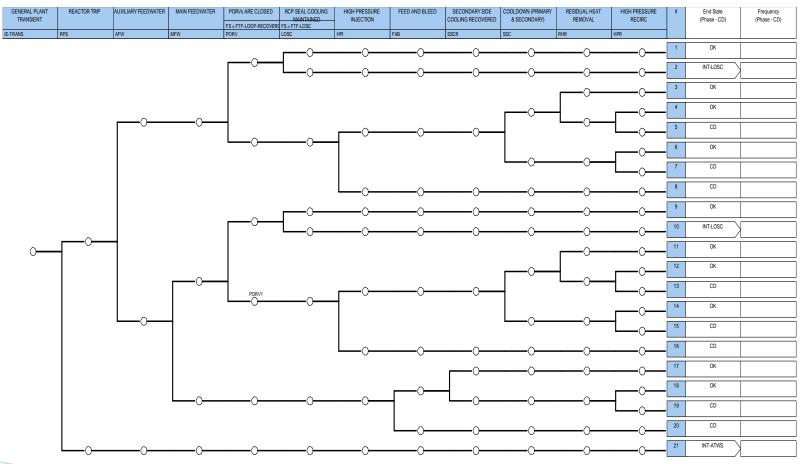
QIAS-P reconstructed architecture based on APR 1400 design

qualified indication and alarm system – safety software design description software requirements specifications systems test document



(III). Consequence Analysis

 In FY-21, consequence analysis has been performed by comparing the changes of CDF after adding integrated FTs of digital RTS and ESFAS to the generic PWR event tree model.



A General PWR Transient Event Tree



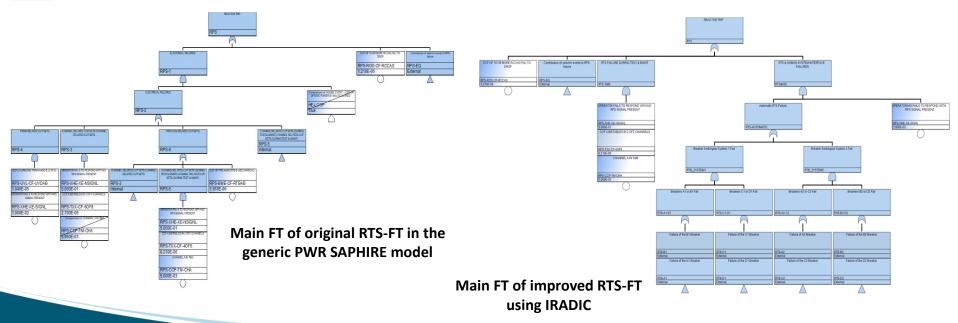
Original and New Fault Trees for Reactor Trip System

Cut sets for the original RTS-FT

#	Prob.	Total %	Cut Sets
1	1.610E-6	37.55	RPS-BME-CF-RTBAB
2	1.343E-6	31.33	RPS-CCP-TM-CHA, RPS-TXX-CF-6OF8, RPS-XHE-XE-NSIGNL
3	1.210E-6	28.22	RPS-ROD-CF-RCCAS
4	1.040E-7	2.43	RPS-UVL-CF-UVDAB, RPS-XHE-XE-SIGNL
5	2.052E-8	0.48	RPS-CCP-TM-CHA, RPS-TXX-CF-4OF6, RPS-XHE-XE-NSIGNL
Total	4.288E-6	100	-

Cut sets for the new RTS-FT

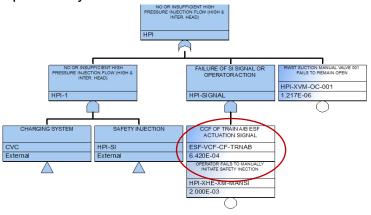
#	Prob.	Total %	Cut Sets
1	1.210E-6	95.25	RPS-ROD-CF-RCCAS
2	2.052E-8	1.62	RPS-CCP-TM-CHA, RPS-TXX-CF-4OF6, RPS- XHE-XE-NSIGNL
3	1.976E-8	1.56	RPS-XHE-XE-SIGNL, RTB-SYS-2-HD-CCF
4	1.976E-8	1.56	RPS-XHE-XE-SIGNL, RTB-SYS-1-HD-CCF
Total	1.270E-6	100	-





Original and New Fault Trees for ESFAS

- In the original generic PWR SAPHIRE model, ESFAS failure is presented using a CCF of the ESF actuation signals in both Train A and B (a 2-division ESFAS).
- Compared with the original ESFAS-FT, the new ESFAS-FT has:
 - A complicated logic to match the 4-division digital ESFAS structure deployed in APR-1400.
 - A significantly reduced failure probability.
- Software CCFs in the new ESFAS-FT do not significantly affect the reliability of digital ESFAS because of the high-redundant design and high reliability of PLC-based digital systems.
- All the failure probabilities of these safety features have been reduced due to the decrease of ESFAS failure probability.



Main FT of HPI failure in the generic PWR SAPHIRE model where CCF of analog ESFAS is considered.

Cut sets for the new ESFAS-FT

FT Name	Prob.	# of Cut Sets
New ESFAS-FT	2.600E-5	13
Original ESFAS-FT	6.420E-4	1

Comparison of the top events with original ESFAS-CCF basic event and improved ESFAS-FT

Ton Front	Probability		# of Cut Sets	
Top Event	Original	New	Original	New
Failure of AFW	1.487E-5	1.240E-5	1539	1551
Failure of AFW-ATWS	2.367E-4	2.343E-4	906	918
Failure of HPI	1.104E-5	9.803E-6	1163	1172
Failure of LPI	8.416E-4	2.258E-4	1567	1579



CDF Reduction by Adding Digital RTS and ESFAS Fault Trees into Event Trees

Results show the CDFs have been greatly reduced.

Event Trees	Original CDF	New CDF	Δ CDF	Δ CDF/ Original CDF
INT-TRANS	1.073E-6	5.795E-7	- 4.935E-7	- 46%
INT-SLOCA	7.784E-8	7.512E-8	- 2.720E-9	- 3.4%
INT-MLOCA	6.279E-7	5.032E-7	- 1.247E-7	- 20%

- By adding the integrated FTs of the 4-division digital RTS and ESFAS into the PRA models, the safety margin increased by the digitalization of HSSSR I&C systems are quantitatively estimated.
 - RTS failure probability is half-reduced from 4.288E-6 to 1.270E-6.
 - LPI (low-pressure injection) failure probability greatly decreases from 8.416E-4 to 2.258E-4 due to the improvement of ESFAS fault tree.

Using IRADIC technology shows deploying advanced digital RTS and ESFAS provides great benefits to plant safety through an increased safety margin to accident management



Summary

INL-IRADIC Technology aims to:

- Develop a best-estimate, risk-informed capability to estimate quantitatively and accurately the safety margin obtained from plant digitalization, especially for the high safety-significant safety-related (HSSSR) DI&C systems.
- Construct a modularized platform for I&C designers, software developers, plant engineers, and risk analysts to efficiently estimate and prevent the risk introduced by CCFs, especially software CCFs.
- Provide technical basis and risk-informed insights to assist NRC and industry in formalizing licensing processes relevant to addressing CCF issues in HSSSR DI&C systems.
- Be an integrated risk-informed tool for vendors and utilities to meet the regulatory requirements and optimize the D3
 applications in the design stage of HSSSR DI&C systems.
- Demonstration results show digitalization of HSSSR I&C systems (e.g., digital RTS and ESFAS)
 provides great benefits to plant safety through an increased safety margin to accident management.
- Future work in FY-22 includes:
 - Building up the capability of software CCF modeling and embeding it into the IRADIC technology.
 - Improving the methodology and demonstration of IRADIC-ORCAS method.
 - Performing uncertainty quantification and validation to better support the best-estimate prediction of safety margins
 (e.g., ΔCDF) obtained by the deployment of DI&C systems.



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