



Adaptive, Active Learning, and Multifidelity Monte Carlo Methods in the MOOSE Stochastic Tools Module

July 2023

Changing the World's Energy Future

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**Prepared for the
U.S. Department of Energy
Under DOE Idaho Operations Office
Contract DE-AC07-05ID14517**

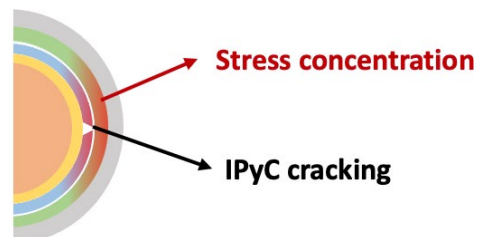
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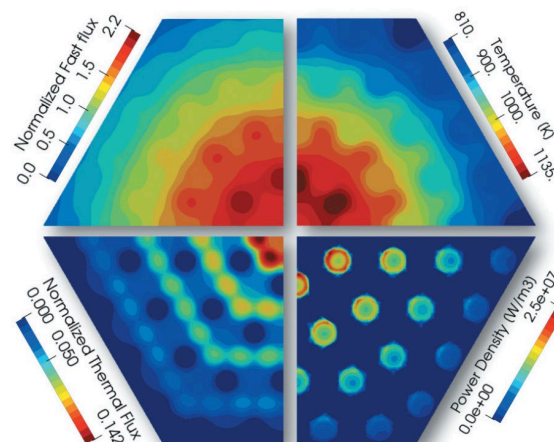
17th US National Congress on Computational Mechanics

Motivation

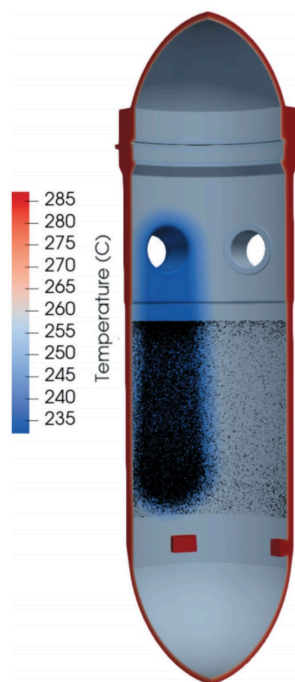
OPyC
SiC
IPyC
Buffer
Kernel



TRISO advanced nuclear fuel model (Jiang et al. 2021)



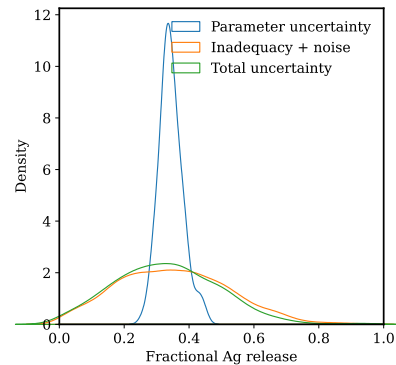
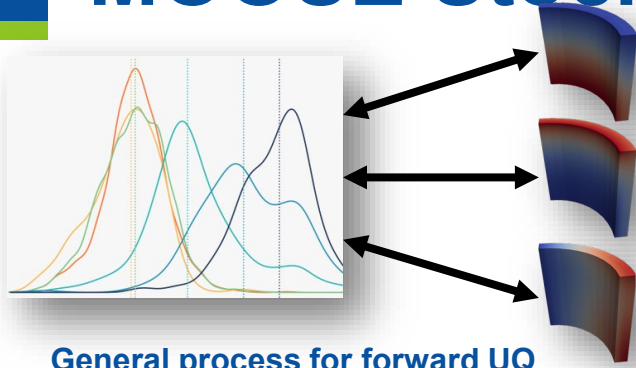
Reactor core simulation of a heat-pipe microreactor (Matthews et al. 2021)



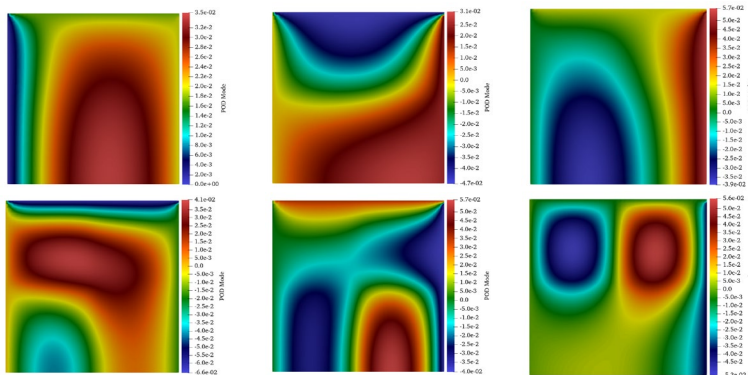
Flaws simulation in a reactor pressure vessel (Spencer et al. 2021)

- In safety-critical fields such as nuclear engineering, failure characterization of advanced reactor technologies considering different sources of uncertainties is important
- Often, failure characterization of advanced reactor technologies and their design optimization involves solving a rare events problem
- Examples: TRISO nuclear fuel, heat-pipe microreactor thermal stresses, reactor pressure vessel embrittlement
- We discuss **recent developments to MOOSE stochastic tools module (STM)** for efficient characterization of rare events

MOOSE Stochastic Tools Module



UQ on modeling TRSIO Particle Ag release

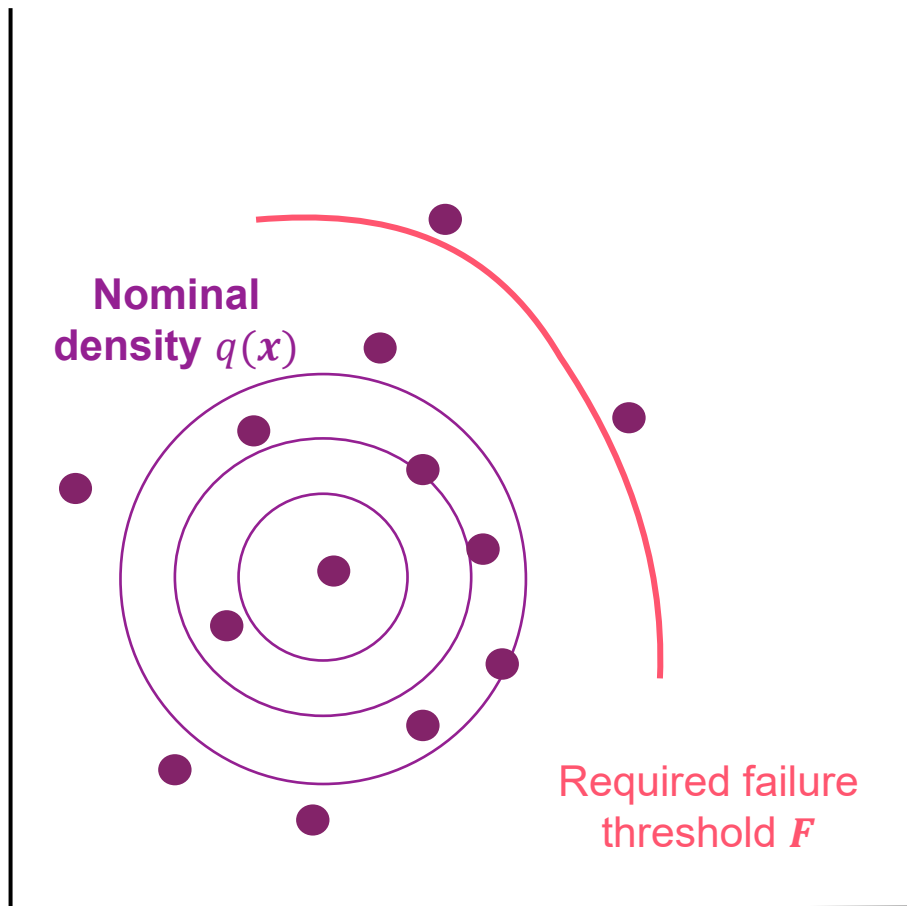


- Provide a **MOOSE interface** for performing stochastic analysis on MOOSE-based models.
- Sample parameters, run applications, and gather data that is both **efficient** (memory and runtime) and **scalable**.
- Perform UQ and sensitivity analysis with **distributed data** with **advanced variance reduction** methods
- **Parallel Scalable Inverse Bayesian UQ** for parameter and model error estimation
- Train meta-models to develop fast-evaluating **surrogates** of the high-fidelity multiphysics model
 - Harness advanced machine learning capabilities through the C++ front end of Pytorch [1]
 - Use active learning models for building surrogates
- Provide a **pluggable** interface for these surrogates.
- Use **POD (Proper Orthogonal Decomposition)-based dimensionality reduction** methods to build mappings between solution variables and latent (low-dimensional) spaces

Sampling for rare events estimation: Monte Carlo

$$P_f = \int_{\tilde{F}(\mathbf{X}) > \mathcal{F}} q(\mathbf{X}) d\mathbf{X} \quad P_f \approx \hat{P}_f = \frac{1}{N_m} \sum \mathbf{I}(\tilde{F}(\mathbf{X}) > \mathcal{F})$$

(\mathcal{F} : Failure threshold; $F(\mathbf{X})$: Model output; $q(\mathbf{X})$: input distributions)



MOOSE STM

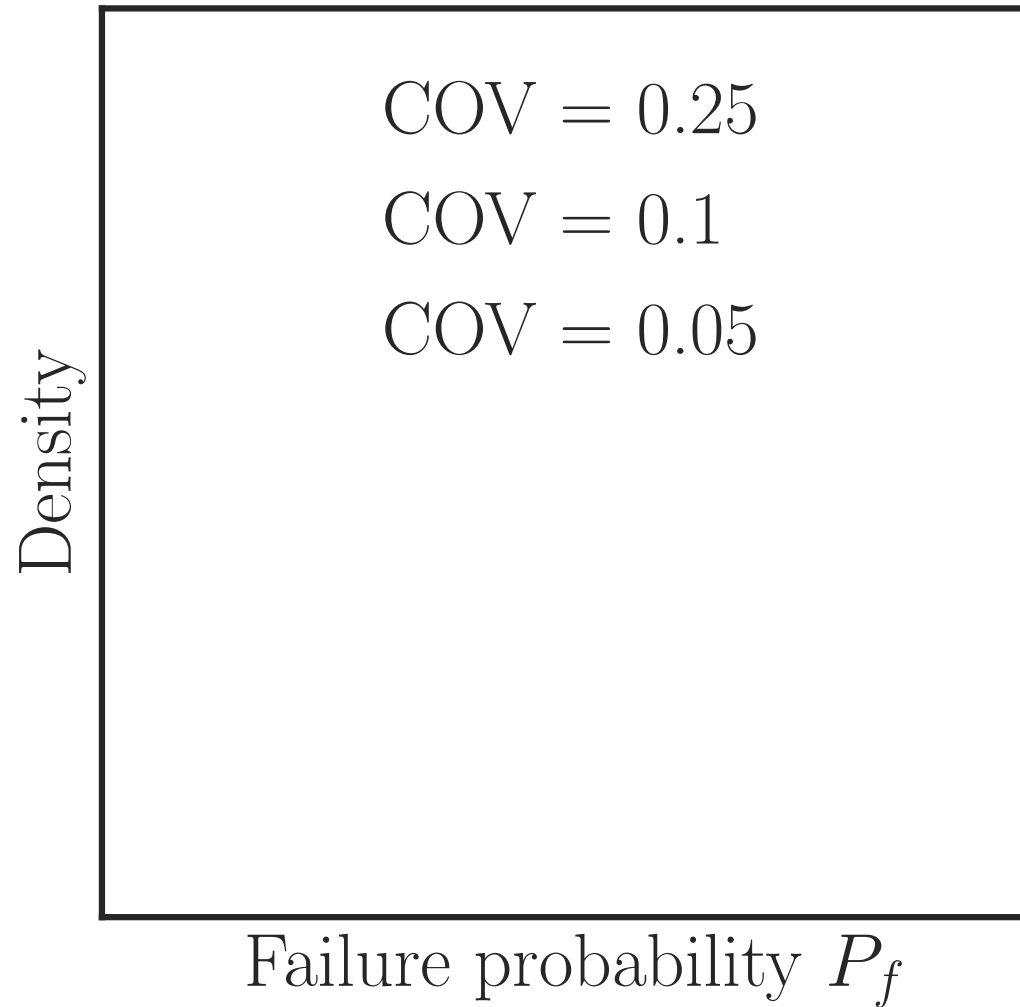
```
[Samplers]
[sample]
  type = MonteCarlo
  num_rows = 100 # Number of Monte
distributions = 'normal_kernel_r
execute_on = 'PRE_MULTIAPP_SETUP'

[]
[]
```

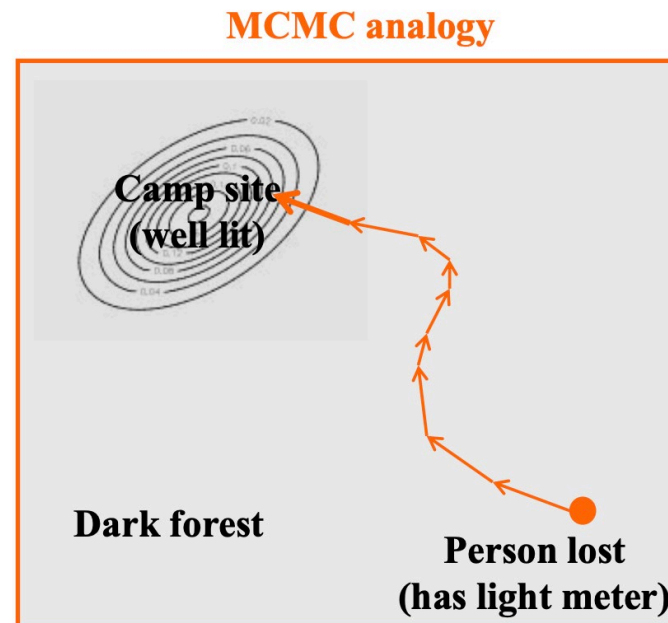
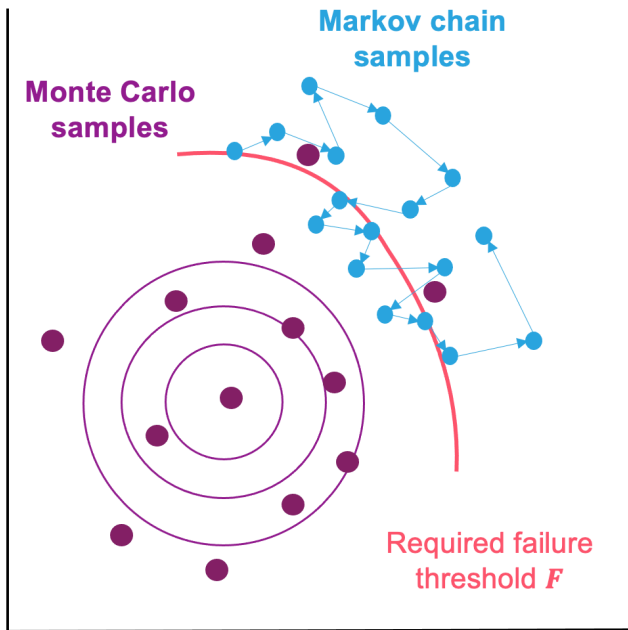
Computationally intractable

- For 2D TRISO fuel model with a P_f of $1\text{E-}4$, Monte Carlo requires ~500 hours on 1000 processors (10% coefficient of variation)
- If the P_f is $1\text{E-}5$, Monte Carlo requires ~5000 hours

Coefficient of variation of failure probability



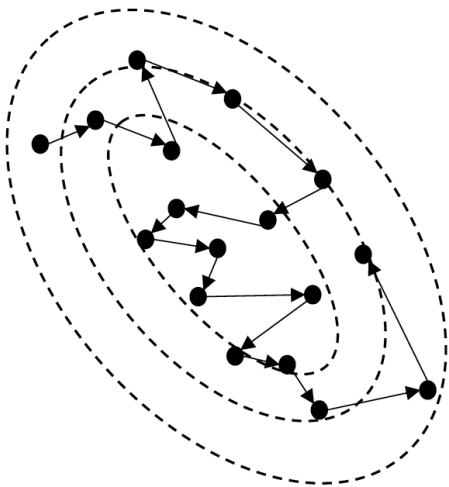
Principle of a Markov chain



- Conditional samples: $q(X|F(X) > F)$
- **Dark forest:** Parameter space
- **Well lit camp site:** Required distribution to be sampled from
- **Light meter:** Acceptance ratio (or transition operator)
- Metropolis-Hastings: popular

Serial and parallel Markov chains

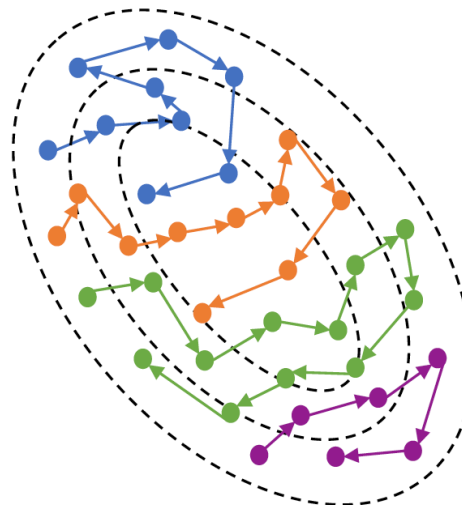
Required
distribution



A Markov chain

Serial: Single Markov chain
Executed on several processors
sample by sample

Required
distribution



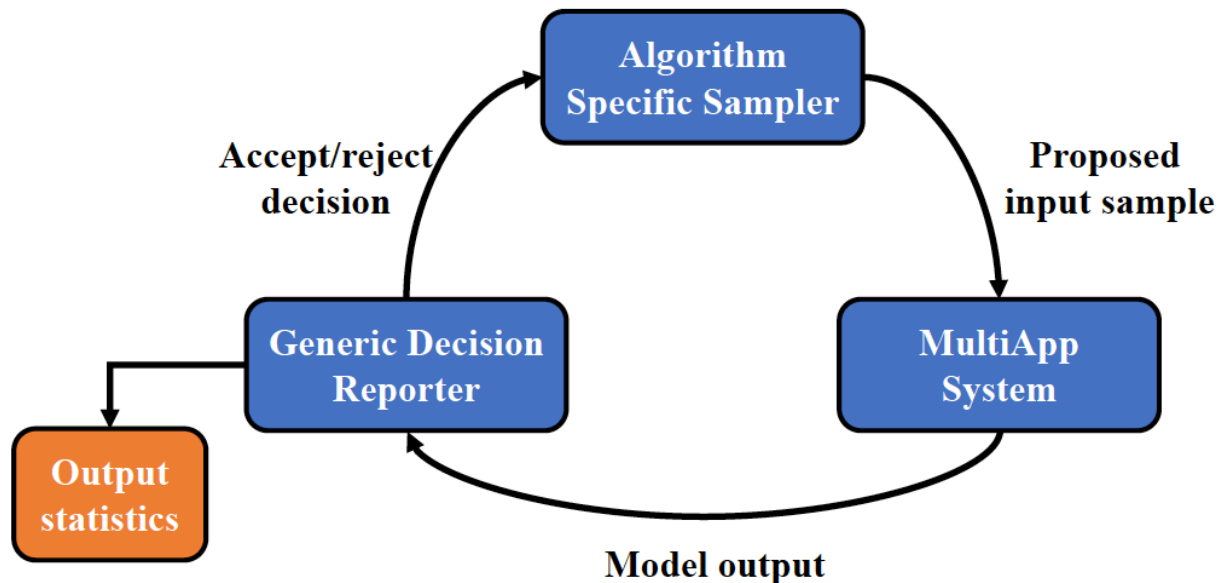
Multiple Markov chains
(shown in different colors)

Parallel: Multiple Markov chains
Executed on several sets of
processors

Important: Parallelization is only achieved across chains but not within a chain.

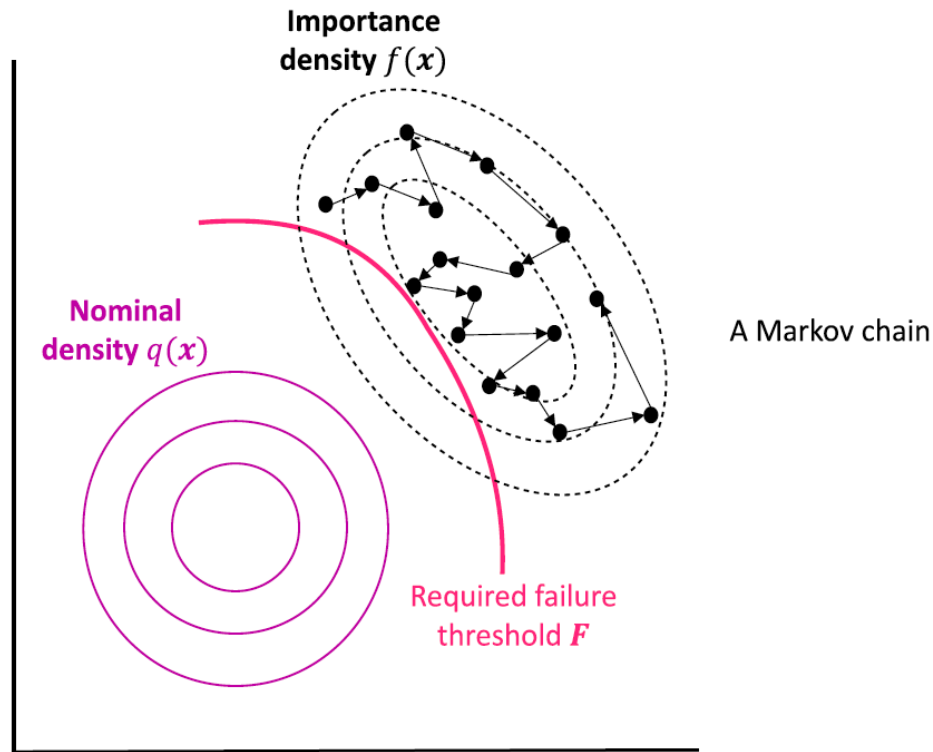
Samples within a Markov chain are history dependent

MOOSE STM design for simulating Markov chains



- Three steps for simulating Markov chains:
 1. Propose a random input sample based on the previous sample
 2. Evaluate the FE model
 3. Accept/reject sample based on FE model output
- **Sampler:** Proposes a random input sample centered around a previously accepted sample. All parameters transformed to standard Normal space.
- **MultiApp:** Evaluate FE model based on the sampler input. Parallelization
- **Reporter:** Consume the subapp output and decide on whether to accept/reject the sampler input proposal
- **Statistics Reporter**

Adaptive importance sampler: theory



- Consists of two phases: training phase and sampling phase
- Transformation to standard Normal space
- **Training phase:** Use Markov chain to sample such that the model always fails
- Construct the importance density $[f(x)]$ using the Markov chain samples
- **Sampling phase:** Sample from the importance density
- Evaluate failure probability and variance using the required equations using samples from the second phase

$$\hat{P}_f^{\text{AIS}} = \frac{1}{N} \sum_{i=1}^N I(F_i(\mathbf{x}) \geq \mathcal{F}) \frac{q(\mathbf{x})}{f(\mathbf{x})}$$

$$\text{Var}(\hat{P}_f^{\text{AIS}}) = \frac{1}{N} \left\{ \frac{1}{N} \sum_{i=1}^N \left[I(F_i(\mathbf{x}) \geq \mathcal{F}) \frac{q(\mathbf{x})}{f(\mathbf{x})} \right]^2 - (\hat{P}_f^{\text{AIS}})^2 \right\}$$

Proposed by Au and Beck (1999)

Adaptive importance sampler: MOOSE STM

Sampler block

```
[Samplers]
  [sample]
    type = AdaptiveImportance
    distributions = 'mu1 mu2'
    proposal_std = '1.0 1.0'
    output_limit = 0.45
    num_samples_train = 30
    std_factor = 0.9
    initial_values = '-0.103 1.239'
    inputs_reporter = 'adaptive_MC/inputs'
  []
[]
```

MultiApp block

```
[MultiApps]
  [sub]
    type = SamplerFullSolveMultiApp
    input_files = sub.i
    sampler = sample
  []
[]
```

Reporter block

```
[Reporters]
  [constant]
    type = StochasticReporter
  []
  [adaptive_MC]
    type = AdaptiveMonteCarloDecision
    output_value = constant/reporter_transfer
    inputs = 'inputs'
    sampler = sample
  []
[]
```

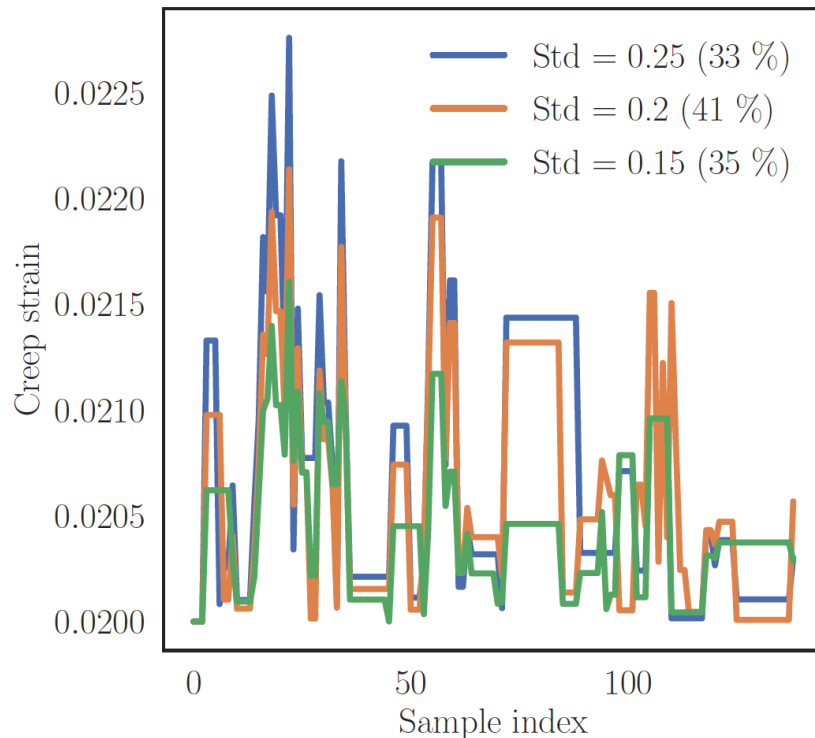
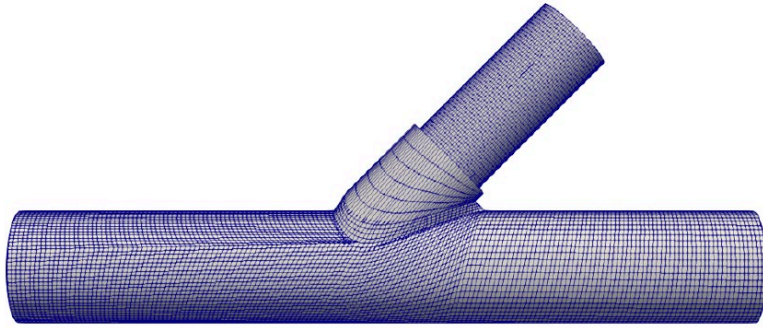
Executioner block (total samples)

```
[Executioner]
  type = Transient
  num_steps = 60
[]
```

Output JSON file

```
{
  "adaptive_MC": {
    "inputs": [
      [
        -0.22230051785267368
      ],
      [
        1.1535106629452407
      ]
    ],
    "output_required": [
      1.0
    ]
  },
  "constant": {
    "reporter_transfer:average:value": [
      0.45366656803460575
    ],
    "reporter_transfer:converged": [
      true
    ]
  },
  "time": 33.0,
  "time_step": 33
},
```

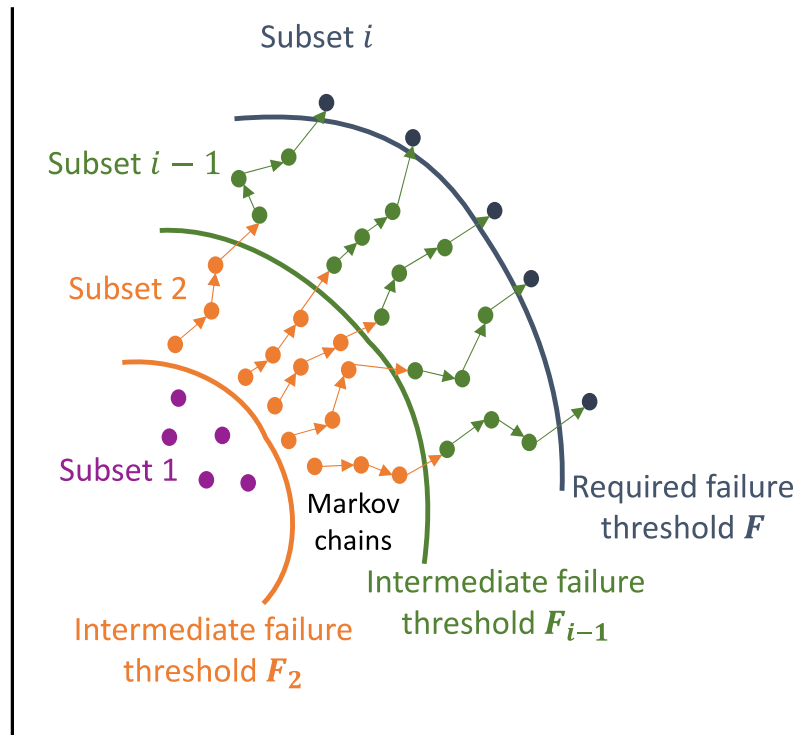
High temperature creep response of a nuclear alloy



- A pipe component in a nuclear reactor exposed to high temperatures. High temperature creep simulations.
- Computational model is expensive, and the creep model has uncertain parameters.
- We want to sample the input parameters such that the creep strain exceeds 2%.
- Regular Monte Carlo takes many model evaluations under random material params so that the 2% creep strain is exceeded sufficiently
- Adaptive Importance Sampler samples from the failure region

(example courtesy of Lynn Munday, Ben Spencer)

Parallel subset simulation: theory



$$P_f = P(F_1) \prod_{i=2}^N P(F_i | F_{i-1})$$

Proposed by Au and Beck (2001)

- AIS limitations: Serial execution; starting sample
- PSS: Expresses small failure probabilities as a product of larger conditional probabilities (of the order 0.1)
- Creates intermediate failure thresholds before the required failure threshold
- An intermediate failure threshold is defined as the $(1-x)$ percentile value of the samples in previous conditional level
- First conditional level: Direct Monte Carlo
- Subsequent conditional levels: Markov Chain Monte Carlo
- **Uses 100s of Markov chains which can be executed in parallel**

Parallel subset simulation: MOOSE usage

Sampler block

```
[Samplers]
[sample]
  type = ParallelSubsetSimulation
  distributions = 'mu1 mu2'
  num_sampllessub = 20
  num_parallel_chains = 2
  output_reporter = 'constant/reporter_transfer'
  inputs_reporter = 'adaptive_MC/inputs'
[]
[]
```

MultiApp block

```
[MultiApps]
[sub]
  type = SamplerFullSolveMultiApp
  input_files = sub.i
  sampler = sample
[]
[]
```

Reporter block

```
[Reporters]
[constant]
  type = StochasticReporter
  outputs = none
[]
[adaptive_MC]
  type = AdaptiveMonteCarloDecision
  output_value = constant/reporter_transfer
  inputs = 'inputs'
  sampler = sample
[]
[]
```

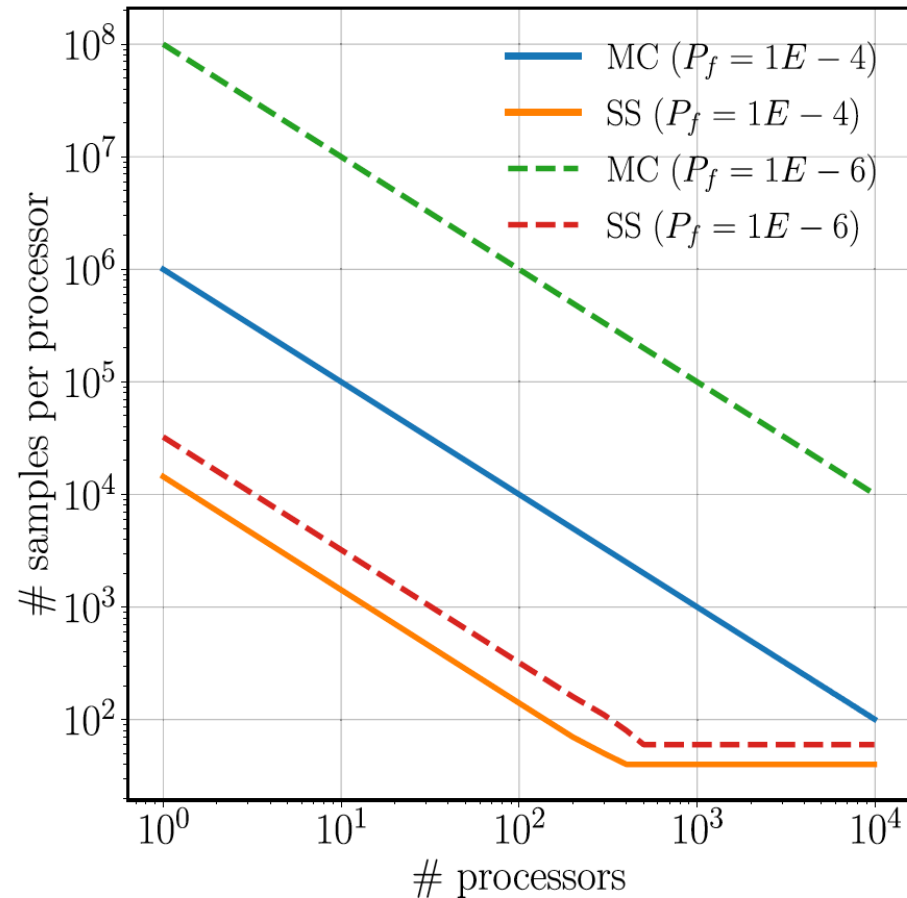
Executioner block (total samples; 3 subsets with 20 samples each)

```
[Executioner]
  type = Transient
  num_steps = 60
[]
```

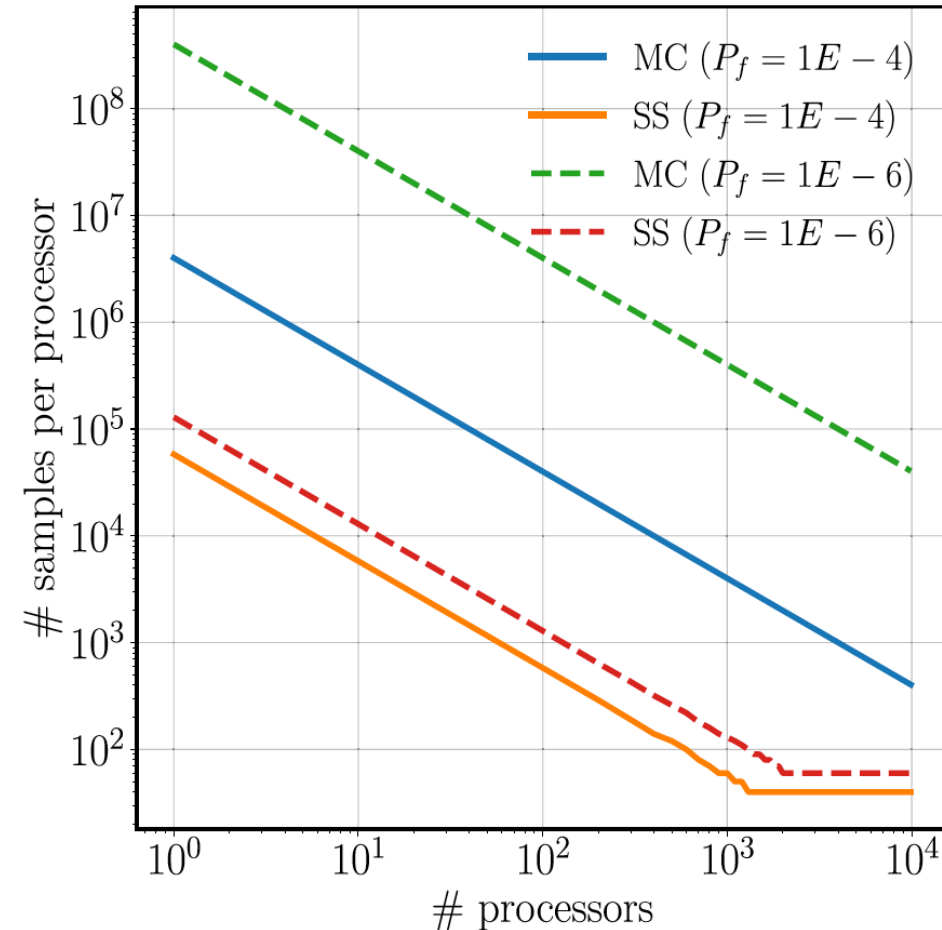
Output JSON file

```
{
  "adaptive_MC": {
    "inputs": [
      [
        0.4756234757587354,
        0.23574626132198995
      ],
      [
        1.6069412882448921,
        1.7647270585523014
      ]
    ],
    "output_required": [
      1.0145830285171529,
      0.9745897531875222
    ]
  },
  "time": 13.0,
  "time_step": 13
},
```


Parallel scalability compared to Monte Carlo



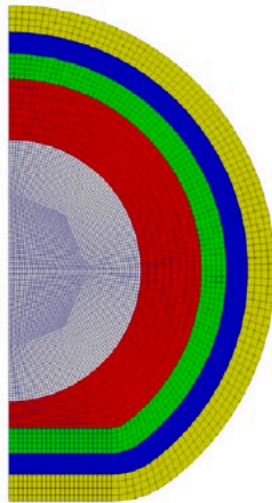
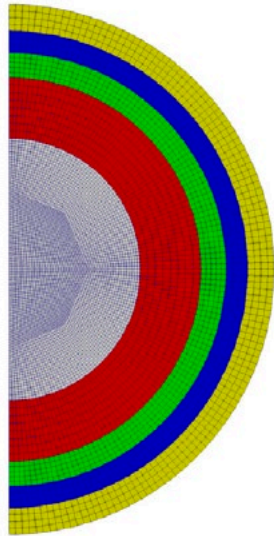
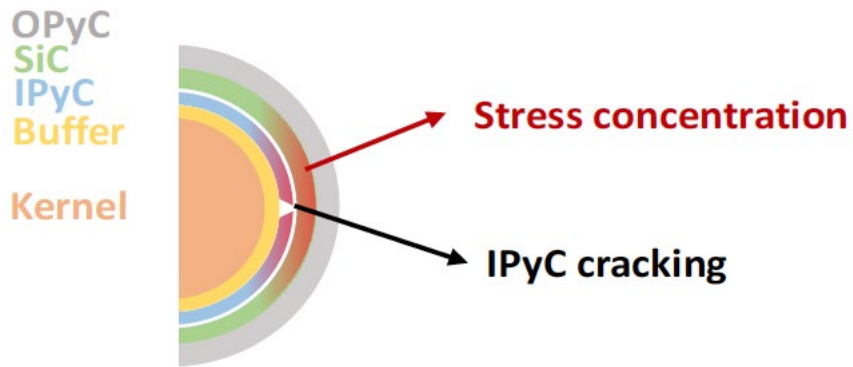
Coefficient of variation: 10%



Coefficient of variation: 5%

(MC: Monte Carlo; SS: subset simulation)

TRISO fuel failure analysis (2D models)



- The 1-D models approximate stresses in the SiC layer based on modification factors
- These factors are calibrated by running evals of the 2-D model
- 2-D model explicitly models cracking in IPyC layer and stress conc. in SiC layer
- More accurate, but mesh density dependent. Therefore, **computationally expensive (~30 mins)**
- Same output: SiC stress – strength (> 0 failure)
- All other inputs for the four models are same as the 1D models

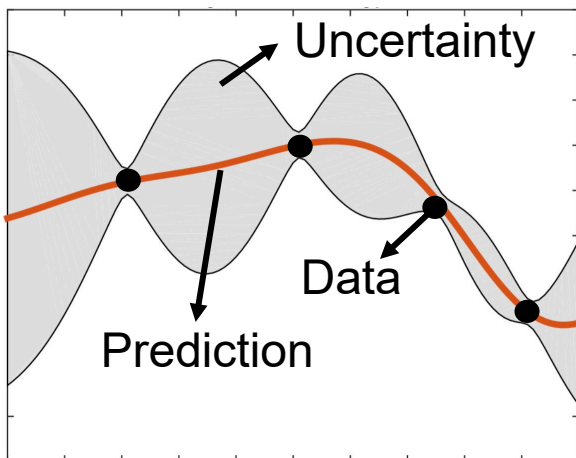
TRISO fuel failure analysis (2D models)

	Weibull	Subset simulation
Model 1	Prob. fail = 0.99E-4	Prob. fail = 1.19E-4 COV = 0.055 N/proc. = 40
Model 2	Prob. fail = 5.86E-5	Prob. fail = 3.4E-5 COV = 0.06 N/proc. = 40
Model 3	Prob. fail = 2.42E-3	Prob. fail = 2.49E-3 COV = 0.045 N/proc. = 40
Model 4	Prob. fail = 3.84E-5	Prob. fail = 3.75E-5 COV = 0.067 N/proc. = 40

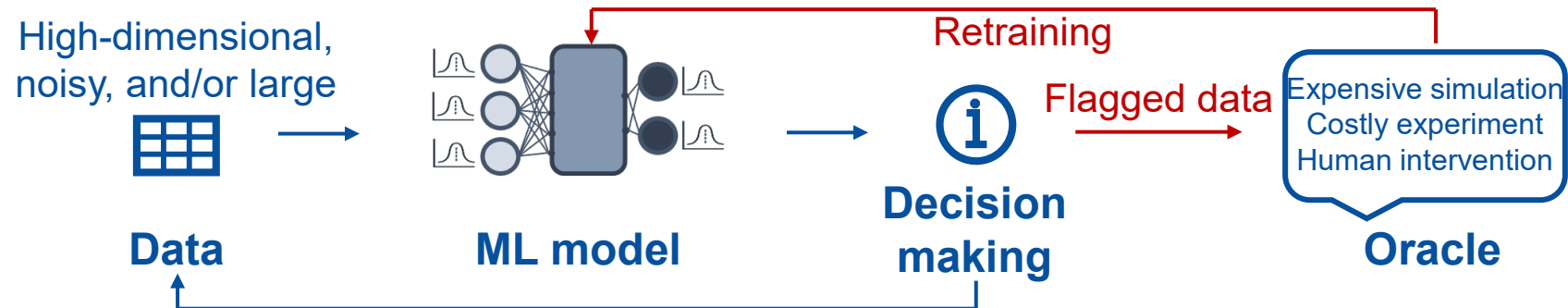
COV: Coefficient of variation; N = number of model evals

- Monte Carlo computationally infeasible
- Reference result is from Weibull theory; closed form. TRISO failure modes restricted to Weibull failure modes.
- Subset simulation results compare well with Weibull theory
- Subset simulation approximately takes 25-30 hours on 1000 procs
- Subset simulation can consider failure modes beyond Weibull (e.g., debonding and kernel migration)

Active learning concept

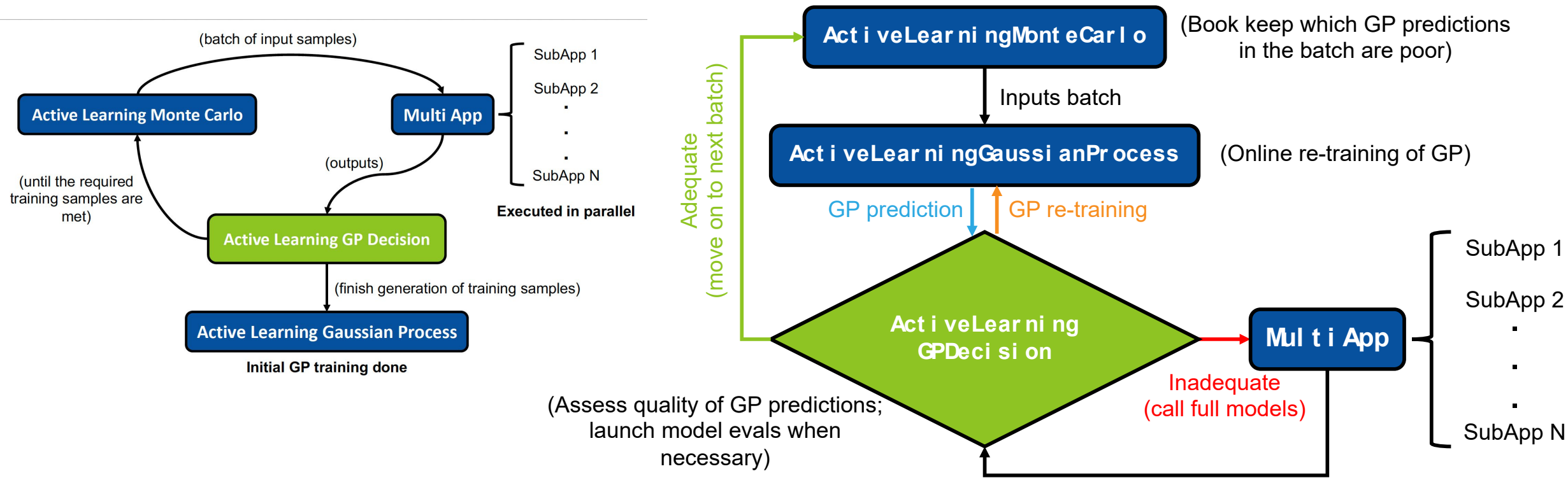


(Credit: Cornell University)

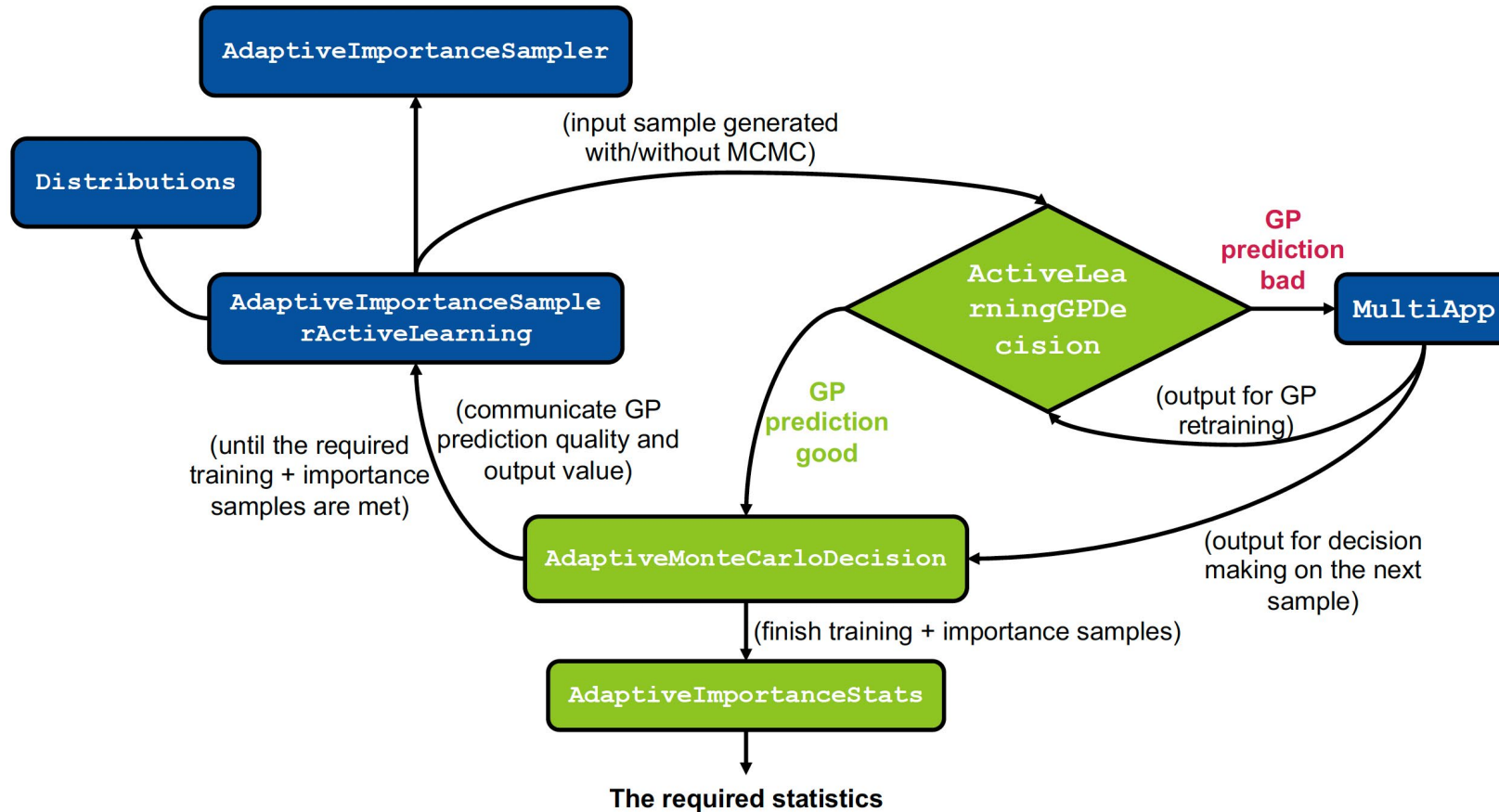


Gaussian Process: Surrogates that know when they're wrong.

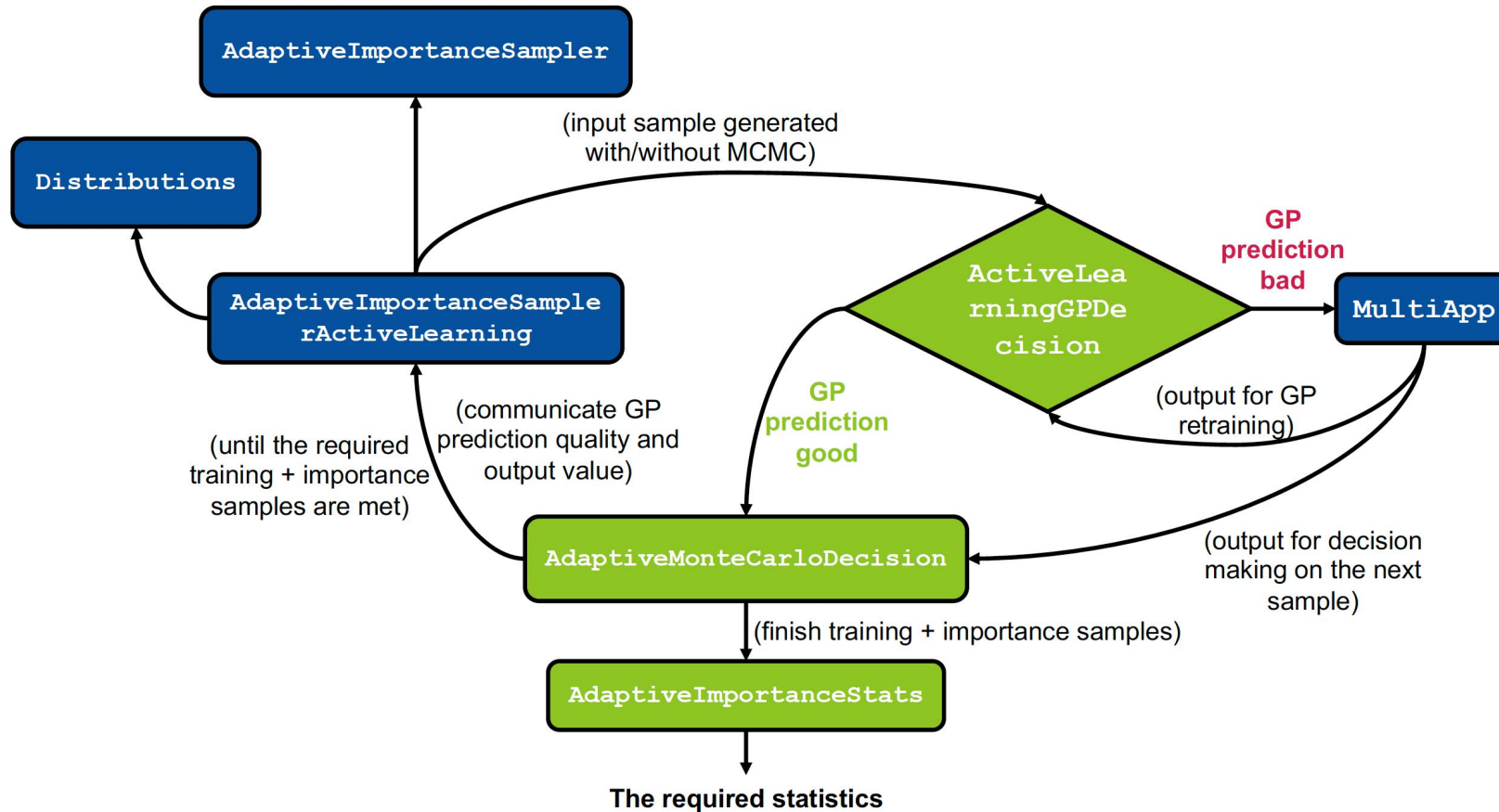
Parallel active learning in MOOSE STM



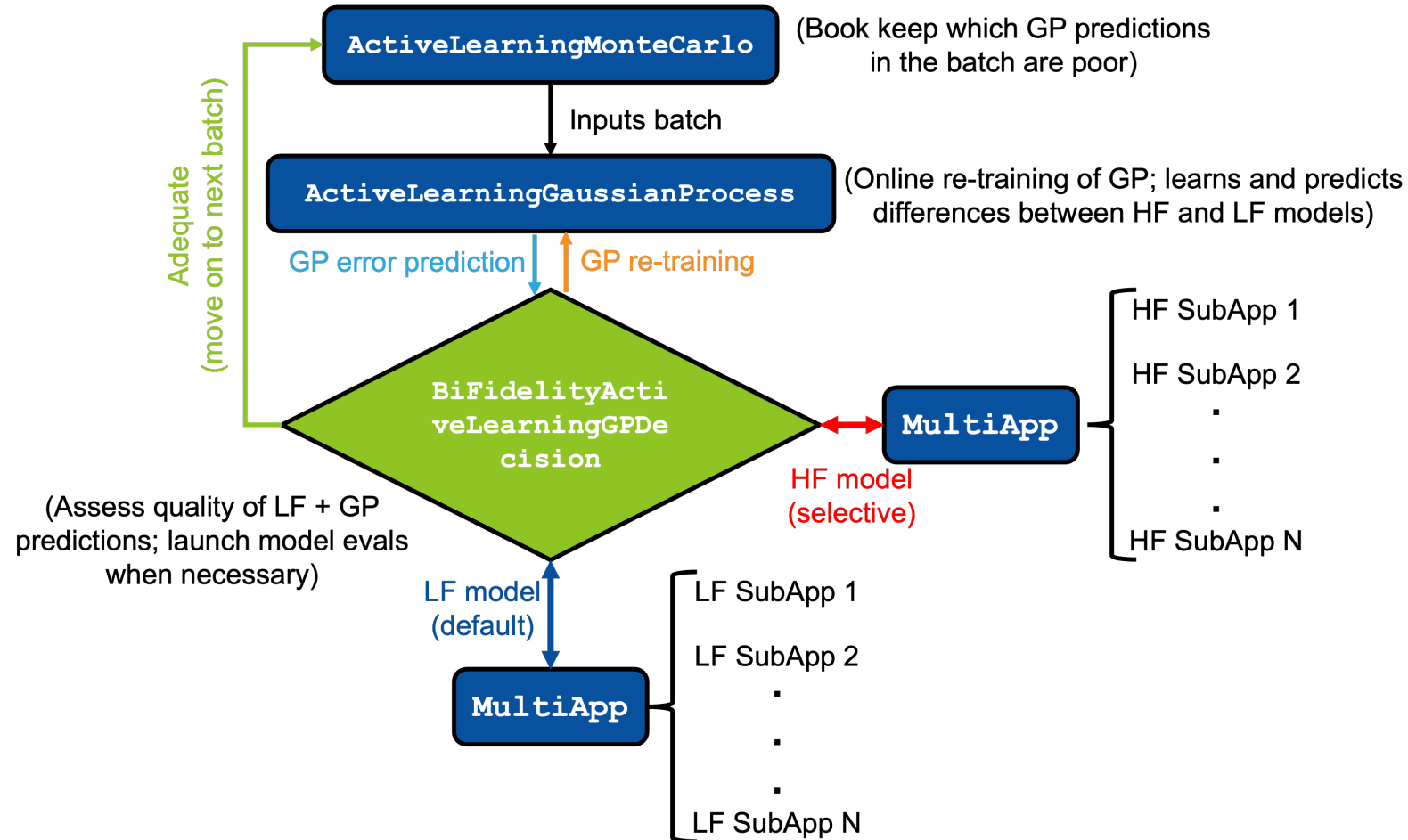
Active learning in importance sampling in MOOSE STM



Active learning in importance sampling in MOOSE STM



Bi-fidelity active learning in MOOSE STM



Application: Bi-fidelity active learning in importance sampling

$$k \frac{d^2 T}{dx^2} = T_b$$

Stochastic parameters

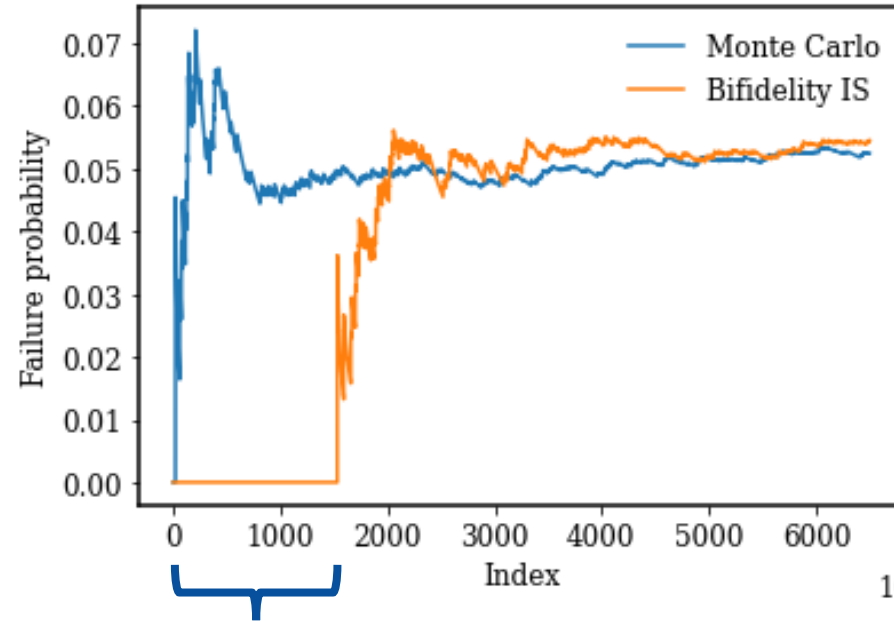
k , T_b , Dirichlet BC

Bi-fidelity models

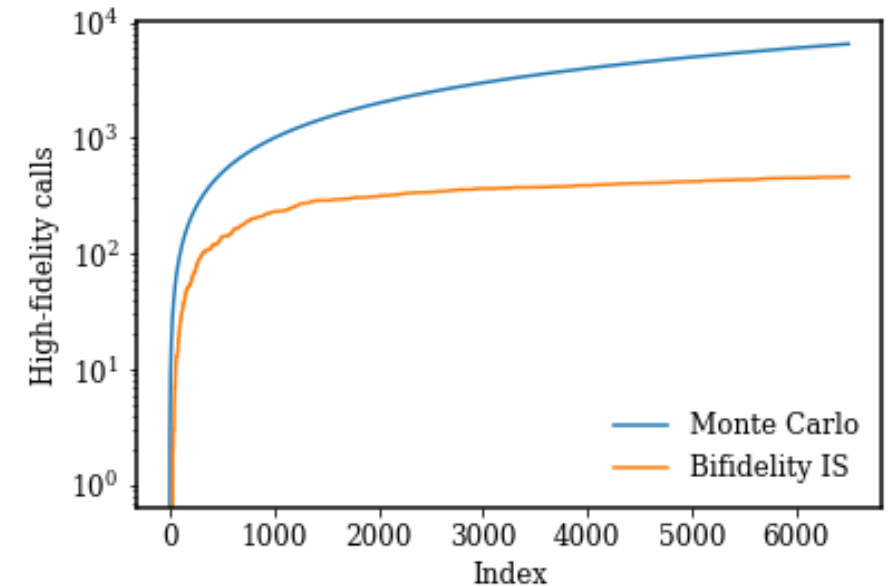
High-fidelity: 100 intervals mesh

Low-fidelity: 5 intervals mesh

Failure threshold is 350.0



Learning the
importance region



Ongoing and future developments in MOOSE STM

- Development of **multiple output Gaussian processes** and linear and non-linear **dimensionality reduction** methods (funded by DOE AMMT)
- Development of a framework for **Bayesian optimization** for reactor design optimization (funded by DOE NEUP)
- Parallelizable inverse UQ capabilities using **Bayesian methods** (funded by DOE NEAMS)
- Parallelizable **active learning learning with MCMC** sampling methods (funded by LDRD and DOE NEAMS)



Thank you!
Questions?